AKHILESH RAJ

akhileshraj91.github.io

in Akhilesh-Raj

G Akhilesh Raj

Akhileshraj91

RESEARCH INTERESTS

- **Reinforcement Learning**: I worked on maximizing the performance parameters under a constrained power supply in HPC nodes. Beginning as a summer internship project, it is now mainstream research area. It can either be posed as an optimal control problem with or without the knowledge of the dynamics or as a reinforcement learning problem that solves the optimization heuristically.
- HPC: Design critical algorithms to propose power caps for the operation of HPC running application thereby pave way to green computing.
- Advanced Test Beds: Developing advanced test beds for testing Cyber-Security Reinforcement Learning Agents trained to tackle ongoing threats to the Operational Technology Networks.

RESEARCH EXPERIENCE

Graduate Research Assistant

Vanderbilt University

📋 Jan 2024 – Present

- Nashville, USA
- Designed and implemented a realistic cyber-physical testbed integrating GridLAB-D (for power distribution simulation), OpenPLC (for programmable logic control), and Mininet (for emulating operational technology (OT) networks).
- Developed and tested Modbus TCP-based communication between SCADA controllers and simulated field devices for real-time data acquisition and control.
- Enabled closed-loop interaction between GridLAB-D and physical control logic via OpenPLC using Python-based middleware for deterministic control and fault injection.
- Emulated cyber-attack vectors and tested their impacts on physical infrastructure to evaluate the resilience and responsiveness of control logic under adversarial scenarios.
- Contributed to the DARPA CASTLE (Cyber Agents for Security Testing and Learning Environments) project, which aims to advance AI-based defense mechanisms for critical infrastructure.
- Facilitated integration of AI agents for anomaly detection and automated mitigation strategies using the developed cyber-physical infrastructure.

W.J Cody Associate

Argonne National Lab

🛗 May 2024 - Aug 2024

- Chicago, USA
- Worked on efficient utilization of edge computational devices while integrating with AI workflows on HPC.
- Developed a data processing algorithm, by designing controller to spawn edge resources based on the arrival speed od data.
- Published the proposed work to IPDPS PAISE-2025 workshop.

Student Sub Contractor

Argonne National Lab

📋 Jan 2023 - Sept 2023

- Remote Position
- Extended the internship works to multiple applications.
- Worked on bringing application agnostic nature to the research.
- Offline reinforcement learning was used to make improvement to power efficiency by incorporating application and hardware agnostic feature.

W.J Cody Associate

Argonne National Lab

🛗 May 2022 – Aug 2022

- Chicago, USA
- Worked on optimizing the performance and power of High Performance Computing (HPC) node.

- A Reinforcement Learning based method implemented using PyTorch with the help of Stable-Baselines-3 was proposed, over the existing Control Theory based approach which yielded results better or equal to the benchmark.
- The RL agent trained using mathematical models of the HPC node was tested on a skylake processor hosted by **Chameleon Cloud**, where the actuation was facilitated with the help of intel RAPL technology.
- The results and the code were tabulated and were made available for publications.

Project Associate

Indian Institute of Science

苗 March 2021 – July 2021

- Bangalore, India
- Worked on the development of an intersection management algorithm in unguarded traffic intersections by using Reinforcement Learning methods. The approach was an alternative to the expensive combined optimization problem that was involved before.
- The constraints were comprised of collision avoidance, passenger safety, intersection safety and a demand factor.
- An important breakthrough that came out of this research was parallelizing the existing python simulations for multicore processors.

Lead Project Engineer

DROPVAULT TECH. PVT. LTD.

🗎 Oct 2020 – Feb 2021

- Worked on creating a functional prototype of a secure package collection system.
- Designed, built and tested a Raspberry Pi based model.
- Lead the team for designing the back-end support.

Research Consultant

BAYESIAN WAYS LLP

苗 Aug 2020 – Oct 2020

- Developed MATLAB and Python based programs for an optimal event scheduler.
- The initial prototype development was done in MATLAB using GUROBI and MOSEK (licensed cvx solvers).
- The solver for the event scheduler (a mixed integer problem), was then developed in Python using CVXPY and OR-TOOLS.

Research Associate

Missouri University of Science and Technology

- **i** Jan 2017 Dec 2019
- Worked on developing a distributed state estimation architecture for multi-agent systems with applications to target tracking using MATLAB.
- With the use of Model Predictive Control (MPC), formulated a control strategy to track the dynamics.
- The project, funded by Dynamic data driven applications of air force office of scientific research, required the detection and tracking of an enemy aircraft, where the dynamics and inputs were considered unknown.

Project Engineer

IDEA Lab, IIT Kanpur

May 2016 - Nov 2016

Kanpur, India

- Worked on this Boeing company funded project for developing computer-vision based automated guided vehicles capable of material handling. This work was able to achieve reduced cost of sensors installed on such a system.
- Worked on designing test bed environments using **ROS2** for simulating Robotic xArm manipulator.

LEADERSHIP AND MENTORING

- Research Mentor Student Inquiry and Research (SIR) Program Illinois Mathematics and Science Academy (IMSA), Oct 2024 – Apr 2025
- Mentored Laksh Patel, a high school researcher, on a cyber-physical systems project integrating OpenPLC, GridLAB-D, and Modbus TCP.
- Guided the development and presentation of "Adversarial Attack Mitigation in Formation Control of Multi-Agent Systems" at the 2025 IMSAloquium, IMSA's flagship research symposium.

Bangalore, India

Rolla, USA

- Kerala, India

- The project introduced Second-Order State Hallucination (SOSH) a novel technique using second-order Taylor expansions to estimate the state of compromised agents in multi-agent systems (MAS). SOSH enables continued stability and formation control under adversarial conditions by disconnecting attacked nodes and substituting their dynamics with hallucinated estimates.
- Demonstrated that hallucinated dynamics preserve exponential stability, mitigating cascading errors in MAS scenarios such as search and rescue, platooning, and disaster response.

EDUCATION

Ph.D in Electrical Engineering (Specialization: Control Systems) Vanderbilt University - CGPA (4.0/4.0)

- **i** July 2021 Dec 2024
- Optimal control of HPC devices a Reinforcement Learning based approach.
- Control of Cyber-Physical-Systems with applications to surrogate models.
- Optimal resource allocation for reducing transmission load using Reinforcement Learning.

M.Tech in Electrical Engineering

- IIT Kanpur CGPA (8.5/10)
- **i** 2014 2016
- Specialisation in control and automation.
- Completed my thesis in computer vision aided Automated Guided Vehicle (AGV).

B.Tech in Electronics and Instrumentation

CET Trivandrum - CGPA (6.56/10)

2009 - 2013

Trivandrum, India

Nashville, USA

Kanpur, India

• Completed my graduation in Applied Electronics and Instrumentation Engineering

PUBLICATIONS

📒 Books

• Raj, Akhilesh, Gandhi, K., Nalla, B. T., & Verma, N. K. (2019). Object detection and recognition using small labeled datasets. In *Computational intelligence: Theories, applications and future directions* (pp. 407–419). Springer.

Journal Articles

• Raj, Akhilesh, Jagannathan, S. [Sarangapani], & Yucelen, T. (2020). Distributed adaptive state estimation and tracking by using active-passive sensor networks. *International Journal of Adaptive Control and Signal Processing*, 34(3), 330–353.

🐣 Conference Proceedings

- Raj, Akhilesh, Das, S., Vardhan, H., Neema, H., Chhokra, A., & Balasubramanian, D. (2025). Autonomous cybersecurity testbed for operational technology networks. In *Proceedings of the 7th workshop on design automation for cps and iot*. doi:10.1145/3722573.3727830
- Raj, Akhilesh, Swann, P., & Gokhale, A. (2025). An offline reinforcement learning based approach for performance aware power reduction. In [under review at hpdc]. ACM.
- Raj, Akhilesh, Swann, P., & Gokhale, A. (2023a). Controlling the energy efficiency of hpc nodes a reinforcement learning based approach. In *Ic2e*. IEEE.
- Raj, Akhilesh, Swann, P., & Gokhale, A. (2023b). Performance-aware power reduction in exascale computing: Leveraging reinforcement learning for unified control of diverse application. In *Ipdps* (to be submitted). IEEE.
- Raj, Akhilesh, Jagannathan, S., & Yucelen, T. (2020). Distributed adaptive state estimation and tracking scheme for nonlinear systems using active passive sensor networks. In *2020 american control conference (acc)* (pp. 2587–2592). IEEE.
- Raj, Akhilesh, Jagannathan, S., & Yucelen, T. (2019a). Distributed state estimation by using active-passive sensor networks. In 2019 american control conference (acc) (pp. 4689–4694). IEEE.
- Raj, Akhilesh, Jagannathan, S., & Yucelen, T. (2019b). Event-triggered adaptive distributed state estimation by using active-passive sensor networks. In 2019 american control conference (acc) (pp. 4695–4700). IEEE.
- Raj, Akhilesh, Gupta, S., & Verma, N. K. (2016). Face detection and recognition based on skin segmentation and cnn. In 2016 11th international conference on industrial and information systems (iciis) (pp. 54–59). IEEE.

- Raj, Akhilesh, Sivaraman, A., Bhowmick, C., & Verma, N. K. (2016). Object tracking with movement prediction algorithms. In 2016 11th international conference on industrial and information systems (iciis) (pp. 285–290). IEEE.
- Verma, N. K., Kumar, G., Siddhant, A., Nama, P., **Raj, Akhilesh**, Mustafa, A., ... Salour, A. (2015). Vision based obstacle avoidance and recognition system. In 2015 ieee workshop on computational intelligence: Theories, applications and future directions (wci) (pp. 1–7). IEEE.
- Verma, N. K., Nama, P., Kumar, G., Siddhant, A., Raj, Akhilesh, Dhar, N. K., & Salour, A. (2015). Vision based object follower automated guided vehicle using compressive tracking and stereo-vision. In 2015 ieee bombay section symposium (*ibss*) (pp. 1–6). IEEE.

Workshops

- Kim, Y., Park, S., Perarnau, S., & Raj, Akhilesh. (2025). Charon: An end-to-end infrastructure for connecting ai@edge to hpc. ACM.
- Raj, Akhilesh, & Swann, P. (2023). *Energy efficient computing*. 15th Joint Laboratory for Extreme-Scale Computing (JLESC)-2023 INRIA, University of Bordeaux, France-March 2023.

🐣 Posters

- Raj, Akhilesh, Canady, R. E., Das, S., Gokhale, A., & Perarnau, S. (2024). Reinforcement learning-based performance-aware energy management in 5g base stations. doi:10.1109/COMSNETS59351.2024.10427091
- Raj, Akhilesh, Perarnau, S., & Gokhale, A. (2024). Application-architecture agnostic efficiency optimization using reinforcement learning. Comminity Workshop on Practical Reproducibility in HPC.

TRAVEL GRANTS RECEIVED

- Super Computing 2024, Atlanta, GA-November 2024
- CCGRID 2024, Philadelphia, PA-May 2024
- Super Computing 2023, Denver, CO-November 2023
- Colosseum Young Gladiators-2023, Institute for the Wireless Internet-of-Things, Northeastern University, Boston, MA-June 2023.
- IC2E Reproducibility Hackathon-2023, 11th IEEE International Conference on Cloud Engineering, Boston University, Boston, MA-September 2023.

RELEVANT COURSES

Computer Networks Social Network Analysis Adaptive Control	Robust Control	Model Integrated Computing
Hybrid and Embedded Systems Linear Control Nonlinear Control	Deep Learning	Reinforcement Learning
Combinatorics and Graph Theory Distributed Systems Modern Control Systems Optimal Control		

STRENGTHS

Technical

- **Python**: Relevant projects include the Reinforcement Learning based control problem solved at ANL, Distributed Systems and Social Network Analysis course projects etc. [available on GitHub]
- **Shell Script**: Experiments related to the HPC node optimization problems (ANL research), performed on Chameleon cloud, which required multiple executions with different configurations used shell scripting. [available on GitHub]
- MATLAB: Formulated and implemented the adaptive control and estimation algorithms, published in American Control Conferences and Journals.
- WebGME: Developed a PetriNet framework for modeling processes which is also hosted on Github.

Personal

- **Team Player**: Worked with different project groups across the globe where I got significant publications and rather, experience. Notable projects include works with Drop Vault Tech. and Bayesian ways.
- Enthusiastic: Eager to learn new subjects through self study and hard-work.
- Vigilant driver with experience over 16 years of driving both in the USA and India.

ACHIEVEMENTS

- 3-MT finalist 2023 organised by GSC at Vanderbilt University.
- Obtained a grant with Argonne National Lab for the year 2023 as the student sub-contractor (graduate).
- Cleared GATE Examination in 2014 with an All India Rank 29.
- Convener/ Coordinator Dhwani'12 (Annual Cultural Fest of CET)
- Sponsorship Committee Convener, Dhrishti'12 (Annual Tech Fest of CET)
- Convener, IEEE WCI-2015 (IEEE conference in computational intelligence, IIT Kanpur)
- Member of adventure sports club, IIT Kanpur, in clearing the Kanchenjunga base camp at an altitude of 4000m.
- Winners Intramural Doubles Badminton tournament, Missouri University of Science and Technology.
- Runners-up in Badminton doubles tournament organized by Missouri S&T CGS.

LANGUAGES

English Malayalam Hindi Spanish

